

dMod – DYNAMICAL MODELING IN R

ICSB2022 SATELITE EVENT

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- What
- How
- How practically
- Why
- Where

- dynamical **Modeling**
- Framework/Toolbox for ODE modeling in R
- Developed by Daniel Kaschek¹

¹D. Kaschek et al., J. Stat. Softw. **88**, 10.18637/jss.v088.i10 (2019)

How

- Symbolic equations
- Define observation function: connect model parameters to observed quantities
- Translate into system of ODEs, compile as C code
- Transformation: (condition dependent) definition of parameters
- Optional: add prior to objective function
- Multi start trust-region fit utilizing gradient and Hessian
- Prediction function composed of modular functions
- Profile likelihood to calculate confident intervals

HOW PRACTICALLY

1. Get data:

	time	name	value	condition
1	0.00000	B_obs	1.0430899	reference
2	10.34483	B_obs	1.8257833	reference
3	20.68966	B_obs	1.8324904	reference
4	31.03448	B_obs	1.7451547	reference
5	41.37931	B_obs	1.7168632	reference

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2. Build equation list EL:

```
el <- NULL
el <- addReaction(el, from = "A", to = "B", rate = "k_AB * A", description = "A to B")
el <- addReaction(el, from = "B", to = "C", rate = "k_BC * B", description = "B to C")
```

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```

3. define observables and error model:

```
observables <- eqnvec(B_obs = "scale_B * B + offset_B")  
errors <- c(B_obs = "sigma_B_obs")
```

HOW PRACTICALLY

4. Compile Models:

```
model <- odemodel(f = el) #ode model
x <- Xs(odemodel = model) #compiled ode model
g <- Y(g = observables, f = el) #observation function
e <- Y(g = errors, f = c(as.eqvec(el), observables), states = names(observables)) #error model
```


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```

5. Set up transformation:

```
> trafo  
Idx      Inner <- Outer  
1         A <- A  
2         B <- B  
3         C <- C  
4      k_AB <- k_AB  
5      k_BC <- k_BC  
7  offset_B <- offset_B  
6   scale_B <- scale_B  
8 sigma_B_obs <- sigma_B_obs
```

HOW PRACTICALLY

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model <- odemodel(f = el) #ode model-
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```

6. Cond. depending paramters, scales, inits:

```
> trafoList
$reference
Idx      Inner <- Outer
1         A <- 10^(A)
2         B <- 0
3         C <- 0
4      k_AB <- 10^(k_AB)
5      k_BC <- 10^(k_BC_reference)
7  offset_B <- 10^(offset_B)
6   scale_B <- 10^(scale_B)
8 sigma_B_obs <- 10^(sigma_B_obs)

$treatment
Idx      Inner <- Outer
1         A <- 10^(A)
2         B <- 0
3         C <- 0
4      k_AB <- 10^(k_AB)
5      k_BC <- 10^(k_BC_treatment)
7  offset_B <- 10^(offset_B)
6   scale_B <- 10^(scale_B)
8 sigma_B_obs <- 10^(sigma_B_obs)
```

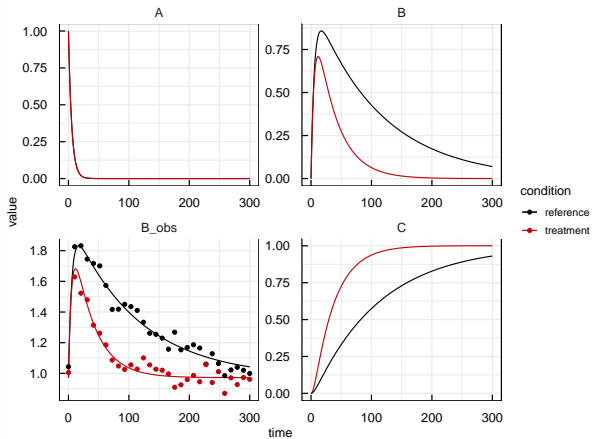
HOW PRACTICALLY

7. Fit:

```
fitOutput <- mstrust(  
  · objfun=obj, ·  
  · center=dMod::msParframe(paramOuter, ·n·=·20, ·seed=1),  
  · studyname="fits", ·  
  · fits=·20, ·  
  · cores=·1  
)·
```

HOW PRACTICALLY

7. Fit:

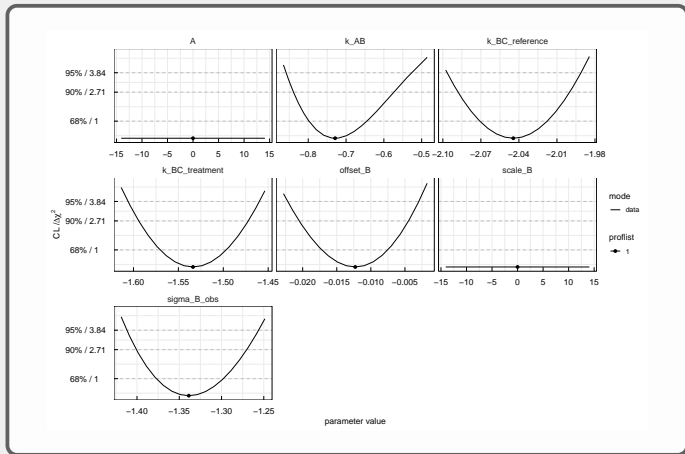


8. Profiles:

```
profiles <- profile(
  obj = obj,
  pars = bestFit,
  whichPar = names(paramOuter),
  cores = 1,
  method = "optimize",
  optControl = list(iterlim = 50)
)
```

HOW PRACTICALLY

8. Profiles:



WHY

- Open source
- Modular
 - ▶ Prediction function build by linking model, observation and transformation
 - ▶ Objective function with "organically" added prior
- Transformation function: focus on handling different treatment/conditions
- slurm-ready
- Reads and speaks P_Etab (under development)

WHERE

■ dMod on CRAN:



■ dMod on github:



■ example model:



■ Recap:

- ▶ Open source model framework in R
- ▶ Optimization based on gradient and hessian
- ▶ Optional prior for obj. function
- ▶ CI from profile likelihood
- ▶ PTab integration

■ Paper:



■ Further questions?

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